

Menoufiya University
Faculty of Engineering
Department of Electrical Engineering

Course: Power Electronics (1)- (ELE 616)
Time : 3-Hour

Date : 31 / 12 / 2016
Marks : 100

Post Graduate Exam (M.sc)

Answer the following questions:

(25-Mark)

Question (1)

1.1) A 230 V, 960 rpm, 20 A, separately excited dc motor has armature circuit resistance and inductance of 1.2Ω and 50 m H respectively. The motor is controlled by a single-phase half-controlled rectifier with source voltage of 230 V, 50 Hz. Calculate no load speeds, and speeds and developed torques on the boundary between continuous and discontinuous conductions for $\alpha = 45^\circ$, and 135° .

1.2) A single- phase semi-converter is operated with an uniform PWM control and is supplied from 220 V, 50 Hz supply. The load current with an average value of I_a is continuous with negligible ripple content. There are four pulses per half cycle, each pulse has a width $\delta = 25^\circ$ and the pulses are started at $\alpha_1 = 10^\circ$, $\alpha_2 = 55^\circ$, $\alpha_3 = 100^\circ$, and $\alpha_4 = 145^\circ$. The modulation index $M=0.8$. Calculate:

- (a) The average output voltage, V_{dc} ;
 - (b) The harmonic factor of input current, HF;
 - (c) The distortion factor, DF;
 - (d) The input power factor, PF.
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Question (2)

(25-Mark)

2.1) A single-phase full-wave controller supplies an RL load. The input rms voltage is $V=220$ V, 50 Hz. The load is such that $L=0.008$ H and $R=2.513\Omega$. The delay angles of thyristors are equal: $\alpha_1 = \alpha_2 = \frac{\pi}{3}$. Determine:

- (a) The conduction angle of thyristor, δ ;
- (b) The rms output voltage, V_o ;
- (c) The rms thyristor current, I_R ;
- (d) The rms output current, I_o ;
- (e) The average current of a thyristor, I_A ;
- (f) The input power factor PF.

(You can use the curves of figures 1,2, and 3)

2.2) a single-phase/ single-phase cycloconverter is supplying from 220V, 50 Hz source. The load resistance is 2.5Ω and load inductance is $L=20$ mH. The frequency of output voltage is 20 Hz. If the delay angles are generated by comparing a cosine signal at source frequency with a sinusoidal reference signal at output frequency. Determine:

P.T.O.

- (a) The rms output voltage;
 - (b) The rms current of each thyristor;
 - (c) The input power factor PF.
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Question (3)

(25-Mark)

3.1) Explain with aid of sketches the operation of the Buck-Boost regulator of Fig. (4), assuming continuous load current $I_a=I_A$.

3.2) The input voltage of Buck-Boost converter in Fig.(4), $V_s=12$ V. The duty cycle $K=0.25$ and the switching frequency is 25 kHz. The inductance, $L=150 \mu H$ and filter capacitance is $C_2=220 \mu F$. The energy transfer capacitance $C_1=200 \mu F$ and inductance $L_1=200 \mu H$. The average load current is $I_a=1.125$ A.

Determine the :

- (a) Average output voltage, V_a ;
 - (b) Peak-to-peak output voltage ripple ΔV_c ;
 - (c) Peak-to-peak ripple current of inductor ΔI ; and
 - (d) Peak current of the transistor, I_p .
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Question (4)

(25-Mark)

A 460 V, 50 Hz, 980 rpm, 6 pole, Y-connected squirrel-cage induction motor has the following equivalent circuit parameters per phase referred to the stator: $R_s=0.29 \Omega$, $X_s=0.21 \Omega$, $X_m=13.3 \Omega$, $R_r'=0.145 \Omega$, $X_r'=0.5 \Omega$.

The motor is supplied from a current source inverter. The flux is maintained at the rated value. Calculate:

1. The stator current and dc link current when the machine operates at rated torque and 50Hz.
2. The inverter frequency and dc link current for a speed of 600 rpm and rated torque.
3. The motor speed, stator current, and dc link current for half of the rated torque and inverter frequency of 30 Hz.

Good Luck

Prof.Dr. Sabry Abdellatif Mahmoud

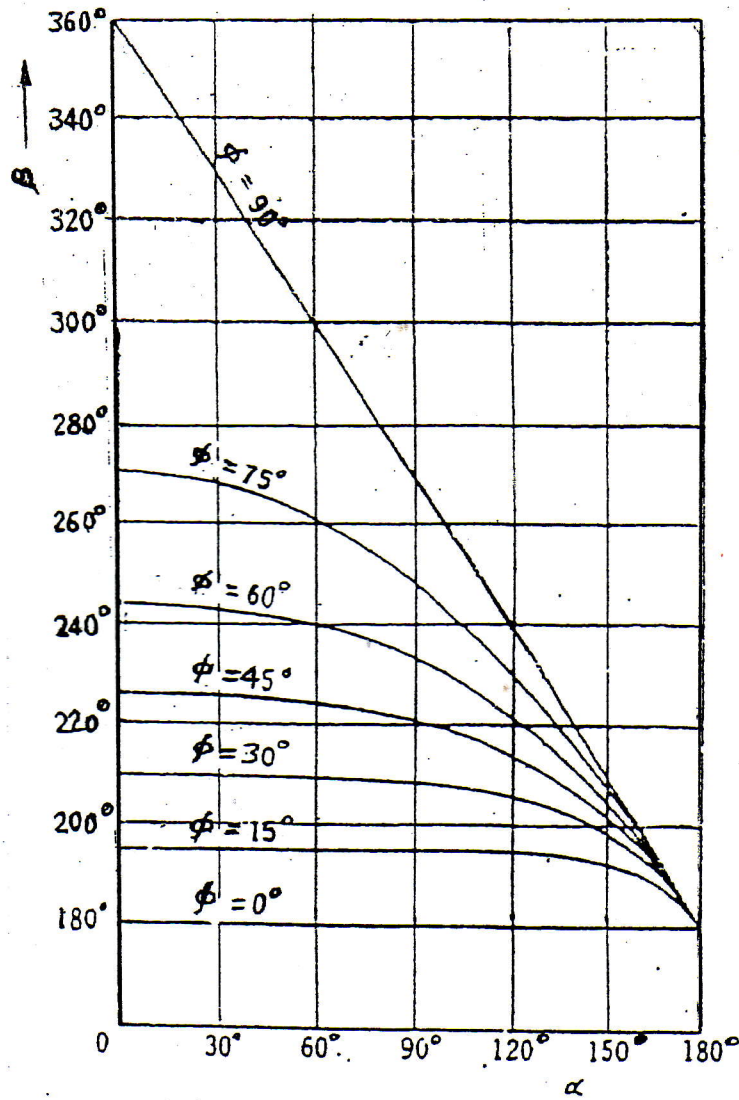


Figure (1) Relation between firing angle (α) and extinction angle (β) for various angle ϕ (load angle).

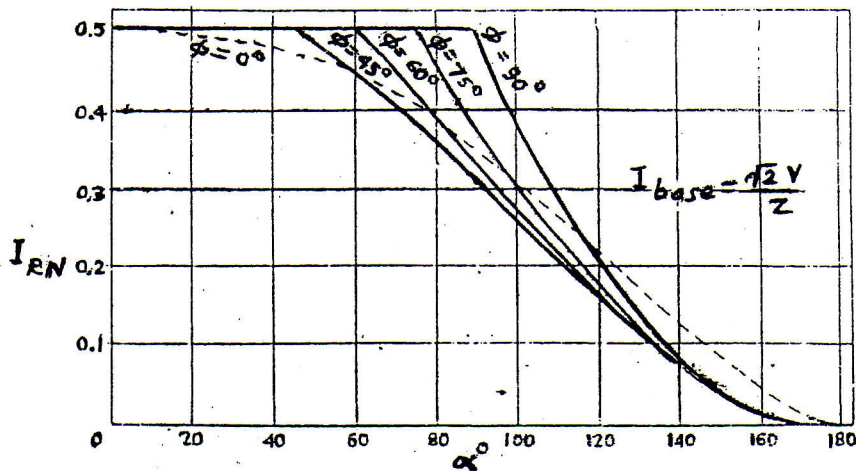


Figure (2) Normalized rms value of the thyristor current (I_{RN}) versus firing angle (α) for various load angle (ϕ).

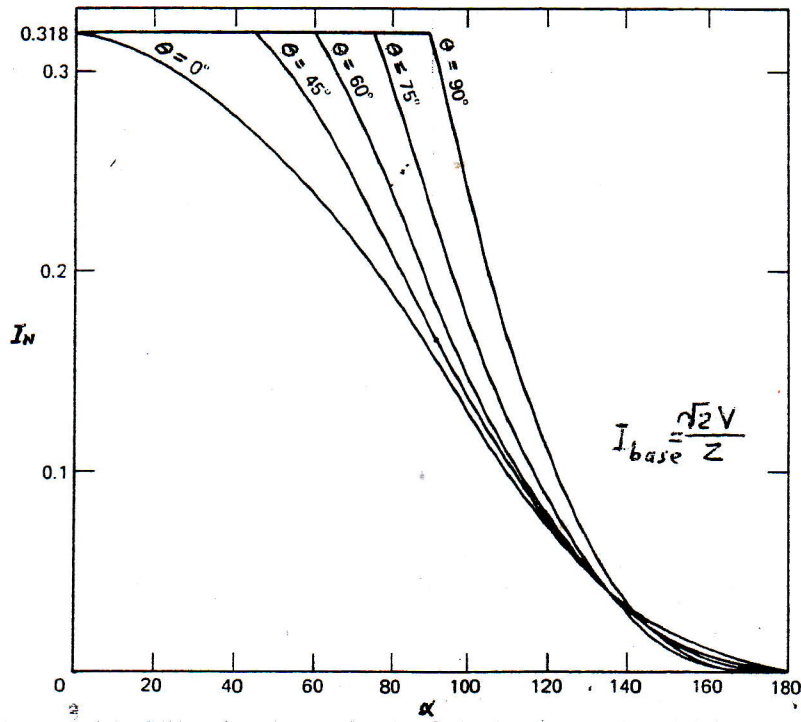


Figure (3) Normalized value of the average thyristor current (I_N) versus firing angle (α) for various load angle (ϕ).

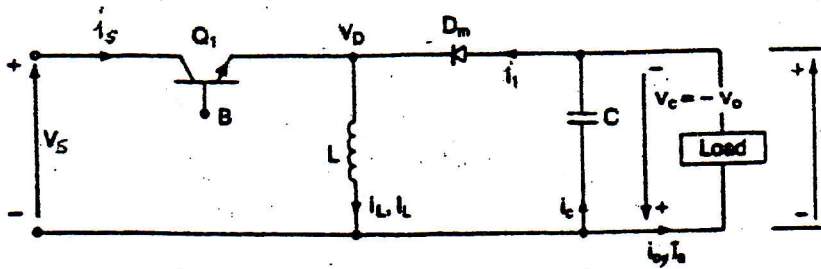


Figure (4) Buck-Boost regulator.

Good Luck
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